Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Currently Amended) A method for editing a geometrical model with a level set modeling surface editor operator, comprising:

defining a level set surface model having at least one deformation thereon to be modified;

performing a level set surface editing operation on a level set surface model, wherein said operation is defined by a level set surface editing operator and is free of edge connectivity data and wherein said performing a level set surface editing operator is defined as a speed function, said function comprising:

a regional constraint function component;

a filter function component;

a surface properties defining function component

wherein said speed function is

$F(x, n, \phi) = D_q(d)C(\gamma)G(\gamma)$, wherein

$D_q(d)$ is said regional constraint function component,

$C(\gamma)$ is said filter function component, and

$G(\gamma)$ is said surface properties defining function component;

γ is a local geometric surface property;

q is a geometric structure;

ϕ is an iso-surface; and

n is a normal of the surface at point x;

wherein said operation modifies the at least one deformation and further including resetting a volumetric representation of said level model after said step of performing a level set surface editing operation to ensure that ϕ is approximately equal to a shortest distance to ~~the~~ a zero level set in ~~the~~ a narrow band.

2. (Original) The method of claim 1 further comprises:

converting an input model into said level set model for said step of performing a level set surface editing operation;

rendering said level set model after said step of performing a level set surface editing operation.

3. (Original) The method of claim 2 wherein said converting step converts said input model from a geometric to a volumetric model by using scan conversion.

4. (Previously Presented) The method of claim 2 wherein said converting step converts said input model by using distance calculations.

5. (Previously Presented) The method of claim 2 wherein said converting step converts said input model by using Sethian's Fast Marching Method.

6. (Original) The method of claim 1 wherein said level set model is represented in a narrow-band distance volume.

7. **(Cancelled)**

8. **(Cancelled)**

9. (Previously Presented) The method of claim 1 wherein said $D_q(d)$ is further defined as having q be a geometric primitive such as a point, a line-segment, or surface and d be the distance from a level set surface of said level set surface model to q.

10. (Previously Presented) The method of claim 1 wherein said γ is a geometric property of a level set surface of said level set surface model, wherein γ is any order property of ϕ.

11. (Original) The method of claim 10 wherein γ represents distance, which is the zero-th order property of ϕ.

12. (Original) The method of claim 10 wherein γ represents normal vector to said level set surface, which is the first order property of ϕ.

13. (Original) The method of claim 10 wherein γ represents curvature of said level set surface, which is the second order property of ϕ.

14. (Previously Presented) The method of claim-1 wherein said regional constraint component defines a region-of-influence.

15. (Currently Amended) The method of claim 14 wherein said region-of-influence is defined by a distance calculation to a geometric primitive such as a point set, a line ~~h e~~ segment, or a surface.

16. (Original) The method of claim 15 wherein said region-of-influence is defined by a distance to an intersection curve point set.

17. (Original) The method of claim 15 wherein said region-of-influence is a super-ellipsoid.

18. (Previously Presented) The method of claim 1 wherein said filter function component is a filter of local geometric surface properties, wherein user can control the behavior of said level set surface editing operator based on a function of a local geometric surface property.

19. (Previously Presented) The method of claim 1 wherein said surface properties defining function component defines the behavior of said level set surface editing operator.

20. (Original) The method of claim 1 wherein said level surface editing operator is a CSG intersection operator.

21. (Original) The method of claim 1 wherein said level surface editing operator is a CSG difference operator.

22. (Original) The method of claim 1 wherein said level surface editing operator is a CSG union operator.

23. (Original) The method of claim 7 wherein said level surface editing operator is a blending operator, wherein blending is constrained by a region-of-influence.

24. (Original) The method of claim 23 wherein said region-of-influence is based on the distance to an intersection curve shared by both input surfaces.

25. (Original) The method of claim 23 wherein said intersection curve is represented by a point set.

26. (Original) The method of claim 23 wherein said blending operator is defined by the function $F_{blend}(x, n, \phi) = \alpha D_q(d)C(K)K$, wherein

α is a user-defined positive scalar that controls the rate of the level set calculation;

$D_q(d)$ is said region-of-influence component with d being the shortest distance from the level set surface to said intersection curve point set;

K is a curvature term; and

$C(K)$ is a filtering function that defines the geometric properties of said blending operator.

27. (Original) The method of claim 23 wherein said blending operator calculates a closest point in a set by using the approximate nearest neighbor search algorithm of Mount and Arya.

28. (Currently Amended) The method of claim 27 wherein said blending operator calculates a closest point in a set by storing a point set in a K-D tree, wherein points in said point set ~~is~~ are ~~uniform~~ uniformly distributed.

29. (Currently Amended) The method of claim 27 wherein said blending operator calculates a closest point in a set by storing a point set in the balanced box decomposition (BBD) tree, wherein points in said point set ~~is~~ are clustered.

30. (Original) The method of claim 7 wherein said level surface editing operator is a smoothing operator, wherein a surface is smoothed by applying motions in a section that reduces local curvature.

31. (Original) The method of claim 30 wherein said smoothing operator is constrained to move outward relative to said surface to smooth said surface by adding material to said surface.

32. (Original) The method of claim 30 wherein said smoothing operator is constrained to move inward relative to said surface to smooth said surface by removing material to said surface.

33. (Original) The method of claim 30 wherein said smoothing operator is converted into a sharpening operator by changing the sign of a scalar term and using said filter function to truncate said speed-function to zero for high values of the curvature.

34. (Original) The method of claim 30 wherein said smoothing operator is defined by the function $F_{smooth}(x, n, \phi) = \alpha D_s(d)C(K)K$, wherein

α is a user-defined positive scalar that controls the rate of the level set calculation;

$D_s(d)$ ensures that said function smoothly goes to zero near the boundary of the region-of-influence;

K is a curvature term; and

$C(K)$ is a filtering function that defines the geometric properties of said smoothing operator.

35. (Currently Amended) The method of claim 34 wherein said region-of-influence of said $D_s(d)$ is defined ~~said~~ by a distance calculation to a geometric primitive such as a point set, a line segment, or a surface.

36. (Original) The method of claim 35 wherein said smoothing operator calculates a closest point in a set by using the approximate nearest neighbor search algorithm of Mount and Arya.

37. (Currently Amended) The method of claim 36 wherein said smoothing operator calculates a closest point in a set by storing a point set in a K-D tree, wherein points in said point set ~~is~~ are ~~uniform~~ uniformly distributed.

38. (Currently Amended) The method of claim 36 wherein said smoothing operator calculates a closest point in a set by storing a point set in the balanced box decomposition (BBD) tree, wherein points in said point set ~~is~~ are clustered.

39. (Original) The method of claim 35 wherein said region-of-influence is a super-ellipsoid.

40. (Original) The method of claim 7 wherein said level surface editing operator is a point set attraction/repulsion operator.

41. (Original) The method of claim 40 wherein said point set attraction/repulsion operator calculates a closest point in a set by using the approximate nearest neighbor search algorithm of Mount and Arya.

42. (Currently Amended) The method of claim 41 wherein said point set attraction/repulsion operator calculates a closest point in a set by storing a point set in a K-D tree, wherein points in said point set ~~is~~ are ~~uniform~~ uniformly distributed.

43. (Currently Amended) The method of claim 41 wherein said point set attraction/repulsion operator calculates a closest point in a set by storing a point set in the balanced box decomposition (BBD) tree, wherein points in said point set ~~is~~ are clustered.

44. (Original) The method of claim 40 wherein said point set attraction/repulsion operator is used to emboss a surface.

45. (Original) The method of claim 1 wherein said level surface editing operator is a morphological editing operator.

46. (Original) The method of claim 2 wherein said rendering uses a volume rendering.

47. (Original) The method of claim 2 wherein said rendering uses Incremental Marching Cubes mesh extraction, which optimizes the mesh extraction by limiting the region which needs to be processed.

48. (Original) The method of claim 2 wherein said input model is a polygon mesh.

49. (Original) The method of claim 48 wherein said polygon mesh is scan converted into a level set model by computing a distance volume, wherein said computing

calculates the closest point on and shortest singed distance to said mesh by solving the Eikonal equation $|\nabla\phi|=1$.

50. (Original) The method of claim 49 wherein said computing a distance volume uses the CPT (closest point) algorithm of Mauch.

51. (Original) The method of claim 2 wherein said input model is a Constructive Solid Geometry (CSG) model.

52. (Original) The method of claim 2 wherein said input model is an implicit model.

53. (Original) The method of claim 2 wherein said input model is a scanned volume.

54. **(Cancelled)**

55. (Currently Amended) The method of claim ~~7~~ 1 wherein level set computations associated with solving said speed function are regionally constrained to a sub-volume defined by the bounding-box of a region-of-influence primitive.